



amc VIBRO

Detection and monitoring of bearings:

a hybrid approach based on vibration analysis and data

Yosra MARNISSI and Mohammed EL-BADAOUI

20/06/23



Agenda

01

|
Context and objectives

02

|
Overview

03

|
Focus on the regression task

04

|
Conclusion and perspectives

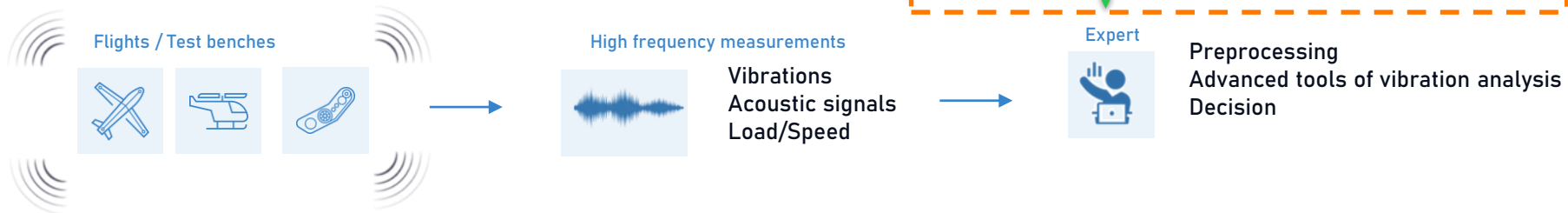


Context and objectives



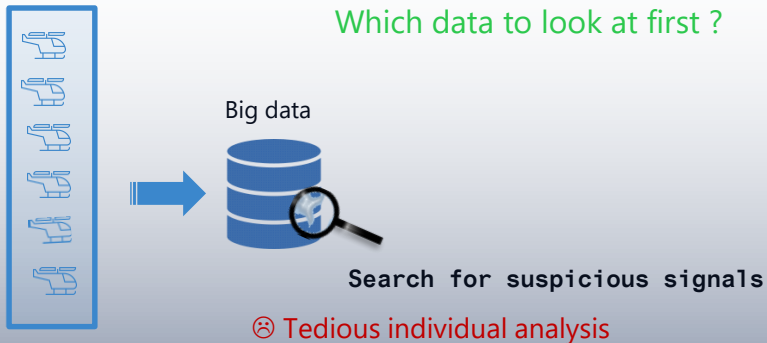
Predictive maintenance

Continuous Health monitoring



Challenges for the Safran Expert

Multiple engines
Multiple flights/tests

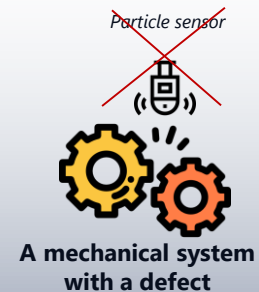


Estimate the size of a defect for prognostic

A degradation model?



⊗ Sensor not always available



Predictive maintenance of bearings

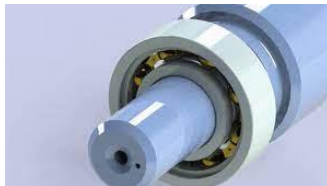
- **Rotating mechanical component**

- Support for gears, shafts, discs, etc.



A bearing

- Equip helicopters, aircraft engines, landing gears, power transmissions systems (AGB, RGB, etc.)



A bearing that is supporting the rotation of a shaft

- **Bearings are prone to failure**

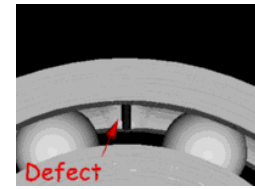
- Difficult environmental conditions (temperature), severe operating conditions (high speed and load)
- Significant consequences: maintenance tools, engine failure



A bearing defect

- **Vibration health monitoring**

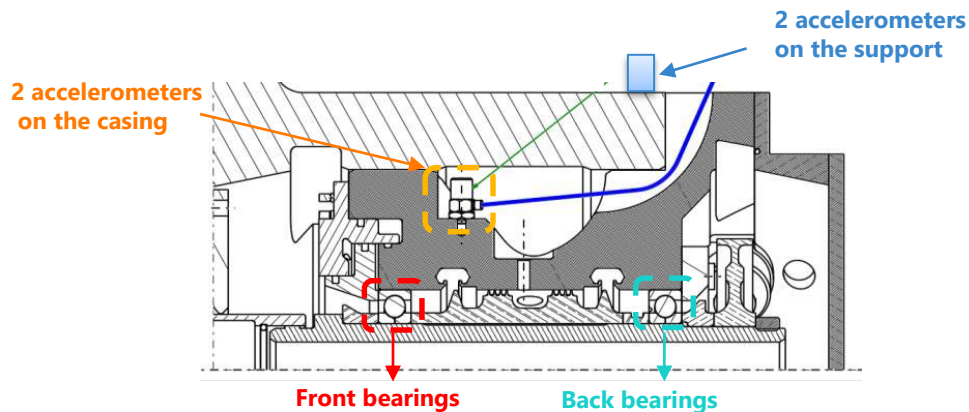
- A defective bearing emits specific vibrations



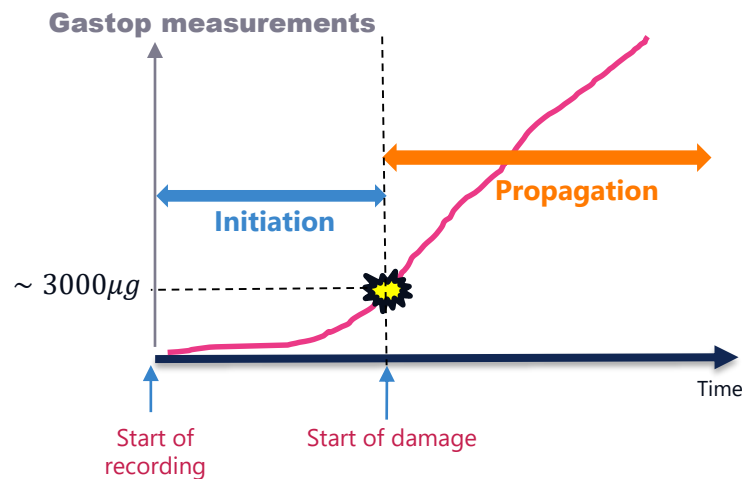
Vibrations caused by a bearing defect

Database

- A test bench in Safran Helicopter Engines (Bordes)
- Inner ring damage of a bearing
- **Number of tested bearings:** 10 bearings
- **Position:** 4 bearings Front/ 6 bearings Back
- **Main sensors**
 - Vibrations: 4 accelerometers (2 casing / 2 support)
 - Gastop: measures the amount of iron particles released by the defective bearing into the oil circuit
 - Test conditions: load, speed
- **Acquisition** : 2 phases
 - Initiation: the defect is created by artificially indenting the inner ring of the bearing
 - Propagation: The defect was detected (partially) by the gastop



Test bench



Test strategy

Objectives and constraints

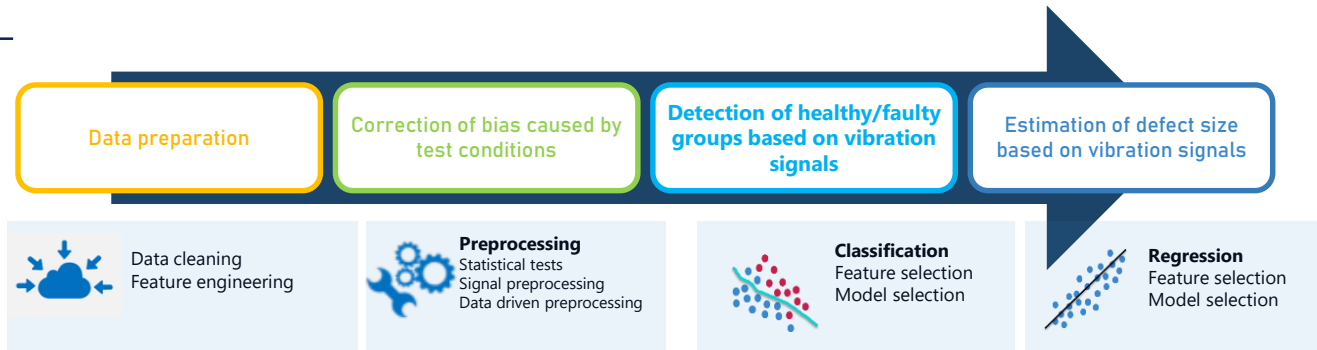
- **Develop an assistance tool to help Safran experts for predictive maintenance of bearings using vibration data**
 1. Indicate to the expert, the signals to be analyzed with priority
 - **A classification task** : target variable = phase either initiation (healthy) or propagation (faulty)
 2. When it comes to estimating the degradation of a bearing, provide the expert with a pre-trained model on previous bearings of the same type
 - **A regression task**: target variable=gastop
 3. Bonus: perform **pre-processing** steps, such as normalizing the data relative to the test conditions
- **A hybrid approach: ML/signal**
 - Leverage physics, expertise, and experts knowledge
 - Simple, reproducible and scalable



Overview



Overview



Step 1: Data preparation



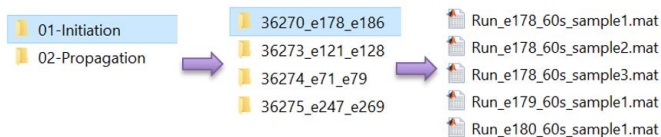
Raw data

- 677 samples
- Each sample is a time series of 3M data points



Data formatting

- Time series segmentation: 33,665 samples
- Replace the time series with approximately 300 indicators
- Load and Gastop are unavailable for multiple tests



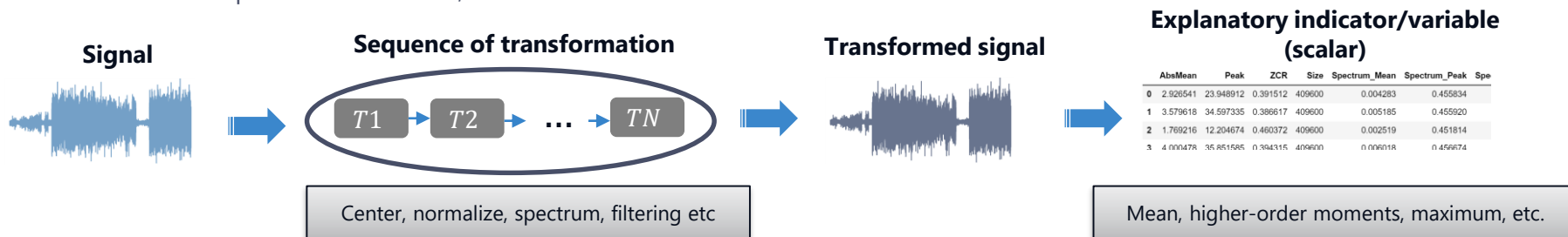
	AbsMean	Peak	ZCR	Size	Spectrum_Mean	Spectrum_Peak	Spe
0	2.926541	23.948912	0.391512	409600	0.004283	0.455834	
1	3.579618	34.597335	0.386617	409600	0.005185	0.455920	
2	1.769216	12.204674	0.460372	409600	0.002519	0.451814	
3	4.000478	35.851585	0.394315	409600	0.006018	0.456674	

Step 1: Data preparation

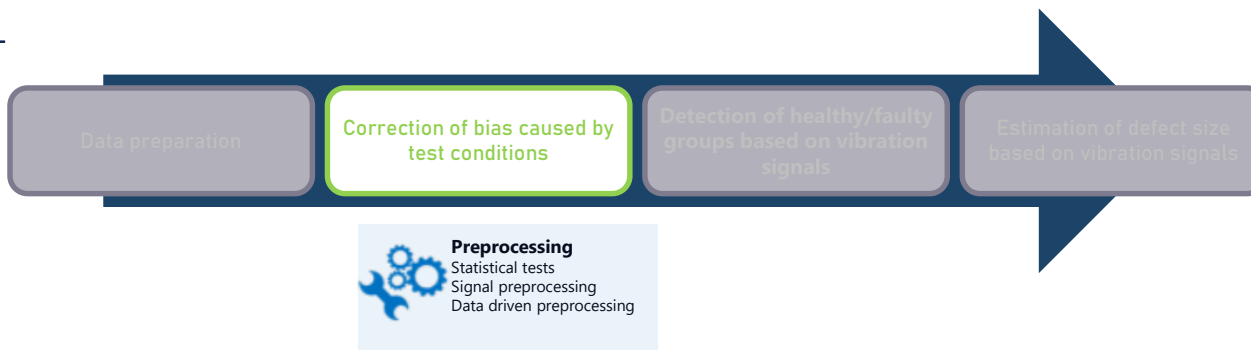


Feature engineering

- **Semi-automatic generation:** a sequence of transformations followed by a scalar indicator
 - Transformations derived from signal processing techniques
 - Simple scalar indicators, statistical in nature



Step 2: Bias correction

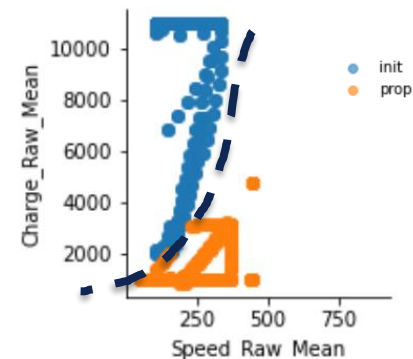


Test conditions bias

- High variability in speed and load
 - Load and speed are **discriminative** variables of the defect phase
 - Health indicators are **sensitive** to test conditions

Consequences on the learning process

- Classification**: Learning the difference in test conditions rather than the defect
- Regression**: Model performance degrades when test conditions differ from training conditions
- Iso-conditions**: Loss of information/not always feasible



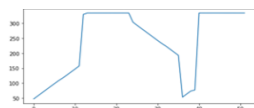
Step 2: Bias correction



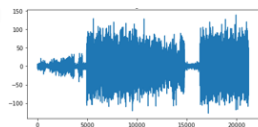
Preprocessing
 Statistical tests
 Signal preprocessing
 Data driven preprocessing

Proposed regularization solutions

- A signal-processing based approach
 - A preprocessing method: NAMVOC
 - Re-compute indicators on corrected data

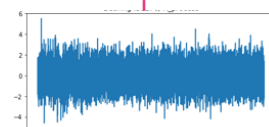


Speed



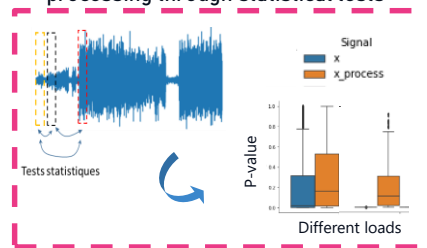
Raw vibration signal

NAMVOC

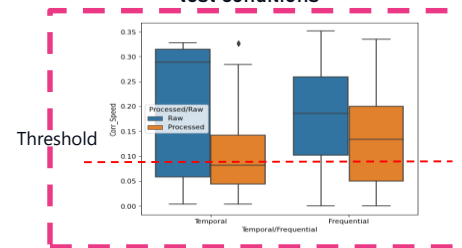


Pre-processed vibration data

Validation of relevance of the pre-processing through statistical tests



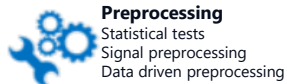
Selection of indicators with the least correlation to test conditions



	AbsMean	Peak	ZCR	Size	Spectrum_Mean	Spectrum_Peak	Spe
0	2.926541	23.948912	0.391512	409600	0.004283	0.455834	
1	3.579618	34.597335	0.386617	409600	0.005185	0.455920	
2	1.769216	12.204674	0.460372	409600	0.002519	0.451814	
3	4.000478	35.851585	0.394315	409600	0.006018	0.456674	

Indicators computed on pre-processed data

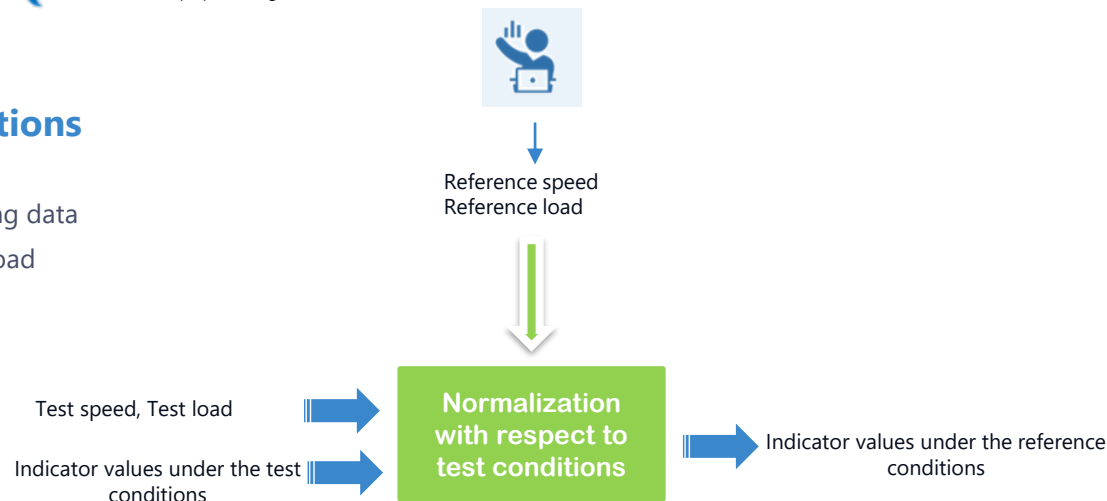
Step 2: Bias correction



▪ Proposed regularization solutions

▪ A data-driven approach

- Train a correction model using training data
 - Need information on speed and load



Step 3: construction of expert assistance models



▪ Choice of the database

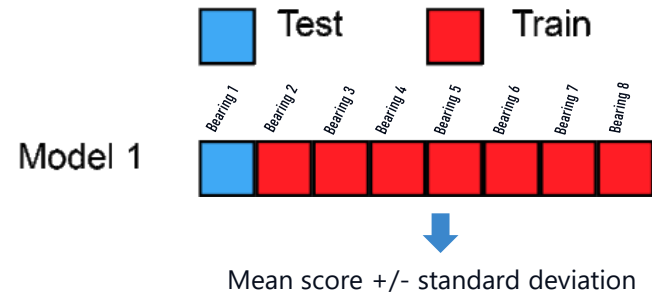
- **Data with iso-conditions:** fewer samples
- **Selected indicators:** fewer variables (indicators)
- **Corrected indicators:** need for load and speed data

▪ Model choice

- **One model = One estimator + A set of indicators**
- Experiments with multiple estimators
- Search for the best parameters through cross-validation
- Search for the best model with progressive feature selection (model with 1 variable, 2 variables, multiple variables, etc.).

▪ Validation choice

- **Leave-One-Bearing-Out :** Validate the model 's ability to generalize to new bearings





Model construction

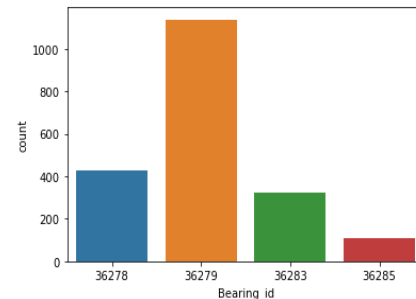
Focus on the regression task



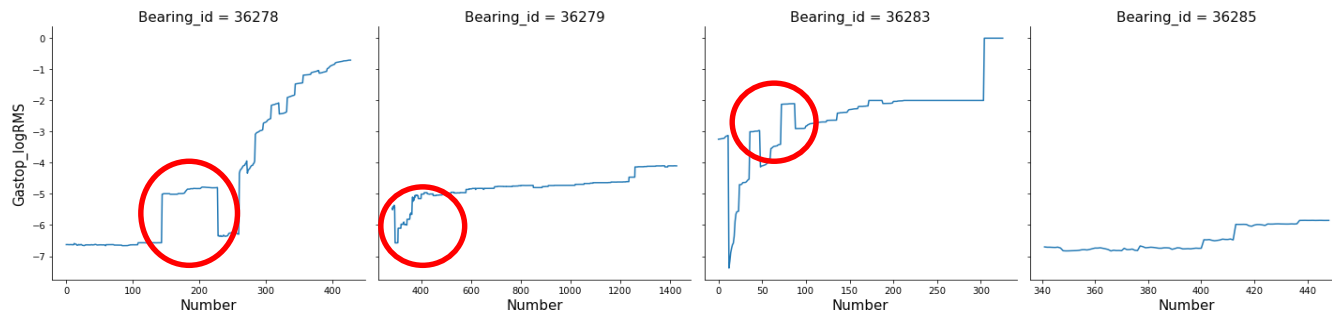
Description (1/2)

▪ In/Out

- *Inputs* : Indicators computed on vibration data
- *Target* : RMS of gastop (in log scale)
- Anomaly \Rightarrow data in the **propagation phase**
- Gastop \Rightarrow only available for 4 bearings
- Some errors in the gastop measurements are currently being ignored



Database with available gastop variable



Target variables

Description (2/2)

▪ Models

- **Estimators:** linear regression, SVR (Support Vector Regression), decision tree, random forest
- **Parameter tuning:** cross-validation
- **Metric:** mean absolute error
- **Validation :** Leave-One-Bearing-Out

▪ Experiments

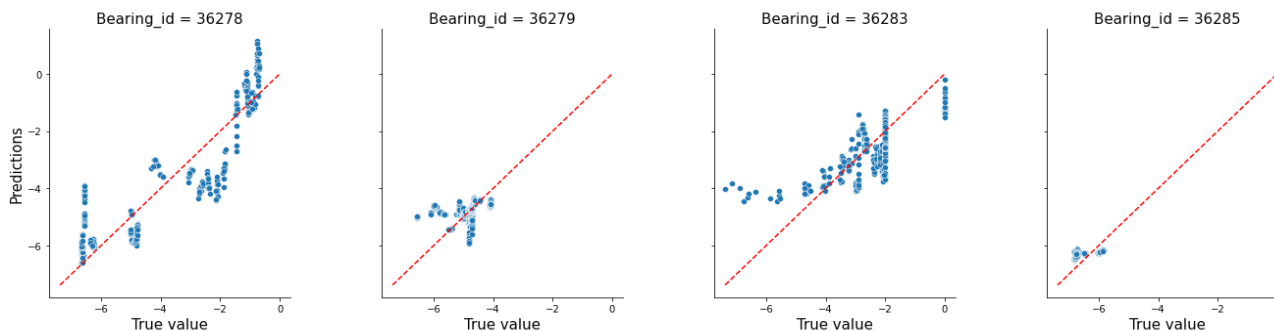
- **Experiment 1:** data with iso-conditions (Not possible)
- **Experiment 2:** selected indicators with the least correlation to test conditions (from the ones computed on pre-processed vibration with NAMVOC)
- **Experiment 3:** corrected indicators using data-driven method

Main results

- **Best model** with 3 explanatory variables
- **Best indicators:** moments on amplitude and frequency spectrum
- Results consistent with expert analysis of some signals
 - ✓ The spectrum becomes richer with the progression of the defect
 - ✓ The characteristic defect frequencies change as the defect progresses
- The proposed correction step provides better variables
- Importance of choosing the sensor

Score (MAE +/- std)

	Selected indicators	Selected indicators + Corrected indicators
Sensor casing	0.85±0.45	0.62 ±0.21
Sensor support	0.75±0.13	0.52 ±0.20



Predicting the gastop value from vibrations



Conclusion and perspectives



Conclusion

▪ Development of an Expert assistance tool for bearing monitoring

- **Preprocess** to normalize the data with respect to test conditions
- **Classify** signals as suspicious/healthy in a dataset
- **Infer** the size of defects from vibrations in the presence of an anomaly

▪ Challenges encountered and Proposed solutions

Task	Challenge	Proposed solution	Limitation/To be improved
Classify/ Infer	Biased database	Correction through signal processing/expert knowledge/statistical learning	How accurate is the database ?
Infer	New problem	Using gastop as a measurement correlated to defect size	Sensitivity of gastop/Source of defect (multiple components)/Gastop measurement errors
Preprocess	Open problem	An assumption and a model learned from the data	The speed and load are measurements that could be modulated by the defect

POWERED BY TRUST
